

# Optimal transportation problem. Applications.

Alexander Kolesnikov

Higher School of Economics

Bonn, Hausdorff Research Institute, 2013

# Equilibrium theory

We follow [CE], [CMcN], [Ekeland].

Assume we are given

1. Compact sets  $X_0 \subset \mathbb{R}^{d_1}$ ,  $Y_0 \subset \mathbb{R}^{d_2}$ ,  $Z_0 \subset \mathbb{R}^{d_3}$
2. Continuous functions  $u(x, z)$ ,  $v(y, z)$  defined on  $X_0 \times Z_0$ ,  $Y_0 \times Z_0$ .  $u(v)$  is assumed to be differentiable w.r.t.  $x$  ( $y$ ).
3. Non-negative finite measures  $\mu_0$  on  $X_0$  and  $\nu_0$  on  $Y_0$ .

Any point  $z \in Z_0$  represents **quality** (or contract types) of indivisible good,  $x \in X_0$  represents consumer type,  $y \in Y_0$  represent producer type.  $\mu$  ( $\nu$ ) is a distribution of consumer (producer) types. To allow for the possibility that some agents choose not to participate, we augment the spaces  $X = X_0 \cup \emptyset_X$ ,  $Y = Y_0 \cup \emptyset_Y$ ,  $Z = Z_0 \cup \emptyset_Z$  by including an isolated point in each: a partner  $\emptyset_X$  for any unmatched sellers, a partner  $\emptyset_Y$  for any unmatched buyers, and the null contract  $\emptyset_Z$ .

# Equilibrium theory

We follow [CE], [CMcN], [Ekeland].

Assume we are given

1. Compact sets  $X_0 \subset \mathbb{R}^{d_1}$ ,  $Y_0 \subset \mathbb{R}^{d_2}$ ,  $Z_0 \subset \mathbb{R}^{d_3}$
2. Continuous functions  $u(x, z)$ ,  $v(y, z)$  defined on  $X_0 \times Z_0$ ,  $Y_0 \times Z_0$ .  $u(v)$  is assumed to be differentiable w.r.t.  $x$  ( $y$ ).
3. Non-negative finite measures  $\mu_0$  on  $X_0$  and  $\nu_0$  on  $Y_0$ .

Any point  $z \in Z_0$  represents **quality** (or contract types) of indivisible good,  $x \in X_0$  represents consumer type,  $y \in Y_0$  represent producer type.  $\mu$  ( $\nu$ ) is a distribution of consumer (producer) types. To allow for the possibility that some agents choose not to participate, we augment the spaces  $X = X_0 \cup \emptyset_X$ ,  $Y = Y_0 \cup \emptyset_Y$ ,  $Z = Z_0 \cup \emptyset_Z$  by including an isolated point in each: a partner  $\emptyset_X$  for any unmatched sellers, a partner  $\emptyset_Y$  for any unmatched buyers, and the null contract  $\emptyset_Z$ .

# Equilibrium theory

We follow [CE], [CMcN], [Ekeland].

Assume we are given

1. Compact sets  $X_0 \subset \mathbb{R}^{d_1}$ ,  $Y_0 \subset \mathbb{R}^{d_2}$ ,  $Z_0 \subset \mathbb{R}^{d_3}$
2. Continuous functions  $u(x, z)$ ,  $v(y, z)$  defined on  $X_0 \times Z_0$ ,  $Y_0 \times Z_0$ .  $u(v)$  is assumed to be differentiable w.r.t.  $x$  ( $y$ ).
3. Non-negative finite measures  $\mu_0$  on  $X_0$  and  $\nu_0$  on  $Y_0$ .

Any point  $z \in Z_0$  represents **quality** (or contract types) of indivisible good,  $x \in X_0$  represents consumer type,  $y \in Y_0$  represent producer type.  $\mu$  ( $\nu$ ) is a distribution of consumer (producer) types. To allow for the possibility that some agents choose not to participate, we augment the spaces  $X = X_0 \cup \emptyset_X$ ,  $Y = Y_0 \cup \emptyset_Y$ ,  $Z = Z_0 \cup \emptyset_Z$  by including an isolated point in each: a partner  $\emptyset_X$  for any unmatched sellers, a partner  $\emptyset_Y$  for any unmatched buyers, and the null contract  $\emptyset_Z$ .

## Equilibrium theory

We follow [CE], [CMcN], [Ekeland].

Assume we are given

1. Compact sets  $X_0 \subset \mathbb{R}^{d_1}$ ,  $Y_0 \subset \mathbb{R}^{d_2}$ ,  $Z_0 \subset \mathbb{R}^{d_3}$
2. Continuous functions  $u(x, z)$ ,  $v(y, z)$  defined on  $X_0 \times Z_0$ ,  $Y_0 \times Z_0$ .  $u(v)$  is assumed to be differentiable w.r.t.  $x$  ( $y$ ).
3. Non-negative finite measures  $\mu_0$  on  $X_0$  and  $\nu_0$  on  $Y$ .

Any point  $z \in Z_0$  represents **quality** (or contract types) of indivisible good,  $x \in X_0$  represents consumer type,  $y \in Y_0$  represent producer type.  $\mu$  ( $\nu$ ) is a distribution of consumer (producer) types. To allow for the possibility that some agents choose not to participate, we augment the spaces  $X = X_0 \cup \emptyset_X$ ,  $Y = Y_0 \cup \emptyset_Y$ ,  $Z = Z_0 \cup \emptyset_Z$  by including an isolated point in each: a partner  $\emptyset_X$  for any unmatched sellers, a partner  $\emptyset_Y$  for any unmatched buyers, and the null contract  $\emptyset_Z$ .

## Equilibrium theory

We follow [CE], [CMcN], [Ekeland].

Assume we are given

1. Compact sets  $X_0 \subset \mathbb{R}^{d_1}$ ,  $Y_0 \subset \mathbb{R}^{d_2}$ ,  $Z_0 \subset \mathbb{R}^{d_3}$
2. Continuous functions  $u(x, z)$ ,  $v(y, z)$  defined on  $X_0 \times Z_0$ ,  $Y_0 \times Z_0$ .  $u(v)$  is assumed to be differentiable w.r.t.  $x$  ( $y$ ).
3. Non-negative finite measures  $\mu_0$  on  $X_0$  and  $\nu_0$  on  $Y$ .

Any point  $z \in Z_0$  represents **quality** (or contract types) of indivisible good,  $x \in X_0$  represents consumer type,  $y \in Y_0$  represent producer type.  $\mu$  ( $\nu$ ) is a distribution of consumer (producer) types. To allow for the possibility that some agents choose not to participate, we augment the spaces  $X = X_0 \cup \emptyset_X$ ,  $Y = Y_0 \cup \emptyset_Y$ ,  $Z = Z_0 \cup \emptyset_Z$  by including an isolated point in each: a partner  $\emptyset_X$  for any unmatched sellers, a partner  $\emptyset_Y$  for any unmatched buyers, and the null contract  $\emptyset_Z$ .

We extend the measures

$$\mu = \mu_0 + (1 + \nu(Y_0))\delta_{\emptyset_X}, \quad \nu = \nu_0 + (1 + \mu(X_0))\delta_{\emptyset_Y}$$

and utility functions

$$u(\emptyset_X, z) = \begin{cases} 0, & z = O_Z, \\ -\infty, & \text{else} \end{cases}, \quad v(\emptyset_Y, z) = \begin{cases} 0, & z = O_Z, \\ +\infty, & \text{else} \end{cases}$$

- Assume we are given a **price system**  $p : Z_0 \rightarrow \mathbb{R}$
- Consumers of type  $x$  maximize in  $z$

$$U(x) = \max_{z \in Z} (u(x, z) - p(z)).$$

- Producers of type  $y$  maximize in  $z$

$$V(y) = \max_{z \in Z} (p(z) - v(y, z)).$$

We extend the measures

$$\mu = \mu_0 + (1 + \nu(Y_0))\delta_{\emptyset_X}, \quad \nu = \nu_0 + (1 + \mu(X_0))\delta_{\emptyset_Y}$$

and utility functions

$$u(\emptyset_X, z) = \begin{cases} 0, & z = O_Z, \\ -\infty, & \text{else} \end{cases}, \quad v(\emptyset_Y, z) = \begin{cases} 0, & z = O_Z, \\ +\infty, & \text{else} \end{cases}$$

- Assume we are given a **price system**  $p : Z_0 \rightarrow \mathbb{R}$
- Consumers of type  $x$  maximize in  $z$

$$U(x) = \max_{z \in Z} (u(x, z) - p(z)).$$

- Producers of type  $y$  maximize in  $z$

$$V(y) = \max_{z \in Z} (p(z) - v(y, z)).$$



We extend the measures

$$\mu = \mu_0 + (1 + \nu(Y_0))\delta_{\emptyset_X}, \quad \nu = \nu_0 + (1 + \mu(X_0))\delta_{\emptyset_Y}$$

and utility functions

$$u(\emptyset_X, z) = \begin{cases} 0, & z = O_Z, \\ -\infty, & \text{else} \end{cases}, \quad v(\emptyset_Y, z) = \begin{cases} 0, & z = O_Z, \\ +\infty, & \text{else} \end{cases}$$

- Assume we are given a **price system**  $p : Z_0 \rightarrow \mathbb{R}$
- Consumers of type  $x$  maximize in  $z$

$$U(x) = \max_{z \in Z} (u(x, z) - p(z)).$$

- Producers of type  $y$  maximize in  $z$

$$V(y) = \max_{z \in Z} (p(z) - v(y, z)).$$

We extend the measures

$$\mu = \mu_0 + (1 + \nu(Y_0))\delta_{\emptyset_X}, \quad \nu = \nu_0 + (1 + \mu(X_0))\delta_{\emptyset_Y}$$

and utility functions

$$u(\emptyset_X, z) = \begin{cases} 0, & z = O_Z, \\ -\infty, & \text{else} \end{cases}, \quad v(\emptyset_Y, z) = \begin{cases} 0, & z = O_Z, \\ +\infty, & \text{else} \end{cases}$$

- Assume we are given a **price system**  $p : Z_0 \rightarrow \mathbb{R}$
- Consumers of type  $x$  maximize in  $z$

$$U(x) = \max_{z \in Z} (u(x, z) - p(z)).$$

- Producers of type  $x$  maximize in  $z$

$$V(y) = \max_{z \in Z} (p(z) - v(y, z)).$$

If the value  $U(V)$  is strictly positive, consumer buys (producer sells) the good item of the maximizing quality  $z$ . Otherwise not participates.

We define

1. **Demand set**  $D = \operatorname{argmax}\{u(x, z) - p(z) | z \in Z\}$
2. **Supply set**  $S = \operatorname{argmin}\{v(y, z) - p(z) | z \in Z\}$
3. **Demand distribution**  $\alpha_{X \times Z}$  is a measure on  $(X, Z)$  carried on the graph of  $D$  with marginal equals to  $\mu$
4. **Supply distribution**  $\beta_{Y \times Z}$  is a measure on  $(Y, Z)$  carried on the graph of  $S$  with marginal equals to  $\nu$

If the value  $U(V)$  is strictly positive, consumer buys (producer sells) the good item of the maximizing quality  $z$ . Otherwise not participates.

We define

1. **Demand set**  $D = \operatorname{argmax}\{u(x, z) - p(z) | z \in Z\}$
2. **Supply set**  $S = \operatorname{argmin}\{v(y, z) - p(z) | z \in Z\}$
3. **Demand distribution**  $\alpha_{X \times Z}$  is a measure on  $(X, Z)$  carried on the graph of  $D$  with marginal equals to  $\mu$
4. **Supply distribution**  $\beta_{Y \times Z}$  is a measure on  $(Y, Z)$  carried on the graph of  $S$  with marginal equals to  $\nu$

If the value  $U(V)$  is strictly positive, consumer buys (producer sells) the good item of the maximizing quality  $z$ . Otherwise not participates.

We define

1. **Demand set**  $D = \operatorname{argmax}\{u(x, z) - p(z) | z \in Z\}$
2. **Supply set**  $S = \operatorname{argmin}\{v(y, z) - p(z) | z \in Z\}$
3. **Demand distribution**  $\alpha_{X \times Z}$  is a measure on  $(X, Z)$  carried on the graph of  $D$  with marginal equals to  $\mu$
4. **Supply distribution**  $\beta_{Y \times Z}$  is a measure on  $(Y, Z)$  carried on the graph of  $S$  with marginal equals to  $\nu$

If the value  $U(V)$  is strictly positive, consumer buys (producer sells) the good item of the maximizing quality  $z$ . Otherwise not participates.

We define

1. **Demand set**  $D = \operatorname{argmax}\{u(x, z) - p(z) | z \in Z\}$
2. **Supply set**  $S = \operatorname{argmin}\{v(y, z) - p(z) | z \in Z\}$
3. **Demand distribution**  $\alpha_{X \times Z}$  is a measure on  $(X, Z)$  carried on the graph of  $D$  with marginal equals to  $\mu$
4. **Supply distribution**  $\beta_{Y \times Z}$  is a measure on  $(Y, Z)$  carried on the graph of  $S$  with marginal equals to  $\nu$

If the value  $U(V)$  is strictly positive, consumer buys (producer sells) the good item of the maximizing quality  $z$ . Otherwise not participates.

We define

1. **Demand set**  $D = \operatorname{argmax}\{u(x, z) - p(z) | z \in Z\}$
2. **Supply set**  $S = \operatorname{argmin}\{v(y, z) - p(z) | z \in Z\}$
3. **Demand distribution**  $\alpha_{X \times Z}$  is a measure on  $(X, Z)$  carried on the graph of  $D$  with marginal equals to  $\mu$
4. **Supply distribution**  $\beta_{Y \times Z}$  is a measure on  $(Y, Z)$  carried on the graph of  $S$  with marginal equals to  $\nu$

If the value  $U(V)$  is strictly positive, consumer buys (producer sells) the good item of the maximizing quality  $z$ . Otherwise not participates.

We define

1. **Demand set**  $D = \operatorname{argmax}\{u(x, z) - p(z) | z \in Z\}$
2. **Supply set**  $S = \operatorname{argmin}\{v(y, z) - p(z) | z \in Z\}$
3. **Demand distribution**  $\alpha_{X \times Z}$  is a measure on  $(X, Z)$  carried on the graph of  $D$  with marginal equals to  $\mu$
4. **Supply distribution**  $\beta_{Y \times Z}$  is a measure on  $(Y, Z)$  carried on the graph of  $S$  with marginal equals to  $\nu$



## Definition

**Hedonic equilibrium:** a pair  $(\alpha, p)$  where  $\alpha$  is a measure on  $X \times Y \times Z$  such that  $Pr_{X \times Z} \alpha$  ( $Pr_{Y \times Z} \alpha$ ) is a demand (supply) distribution.

Define a **cost function** ("surplus function")

$$s(x, y) = \sup_z (u(x, z) - v(y, z)).$$

Assume that the supremum is attained for every  $(x, y)$  that the set

$$Z(x, y) = \operatorname{argmax}((u(x, z) - v(y, z)) | z \in Z)$$

is compact, non-empty, and depends hemicontinuously on  $(x, y)$ . Then one can find a measurable selection  $z_0(x, y)$  of the multivalued mapping

$$(x, y) \rightarrow \operatorname{argmax}((u(x, z) - v(y, z)) | z \in Z)$$

This problem can be viewed as a continuous **matching problem**: every buyer (seller) looking for a best partner.

**Ekeland.** There exists an (in general non-unique) equilibrium.

**Chiappori, McCann, Nesheim.** Existence of equilibrium can be established by methods of the transportation theory.

### Theorem

*Let  $\gamma$  solve the primal and  $(q(x), r(y))$  solve the dual transportation problem for the cost  $s(x, y)$*

$$\int q d\mu + \int r d\nu \rightarrow \min, \quad q(x) + r(y) \geq s(x, y).$$

*Then there exists  $p(z)$  satisfying*

$$\inf_y \left\{ v(y, z) + r(y) \right\} \geq p(z) \geq \sup_x \left\{ u(x, z) - q(x) \right\}. \quad (1)$$

*With  $\gamma \circ (x, y, z_0)^{-1}$  any such  $p$  forms an equilibrium pair.*

This problem can be viewed as a continuous **matching problem**: every buyer (seller) looking for a best partner.

**Ekeland.** There exists an (in general non-unique) equilibrium.

**Chiappori, McCann, Nesheim.** Existence of equilibrium can be established by methods of the transportation theory.

### Theorem

Let  $\gamma$  solve the primal and  $(q(x), r(y))$  solve the dual transportation problem for the cost  $s(x, y)$

$$\int q d\mu + \int r d\nu \rightarrow \min, \quad q(x) + r(y) \geq s(x, y).$$

Then there exists  $p(z)$  satisfying

$$\inf_y \left\{ v(y, z) + r(y) \right\} \geq p(z) \geq \sup_x \left\{ u(x, z) - q(x) \right\}. \quad (1)$$

With  $\gamma \circ (x, y, z_0)^{-1}$  any such  $p$  forms an equilibrium pair.

**Remark:** note that the statement of the dual problem is slightly different from the standard formulation (but equivalent).

**Proof:** The solution  $(q, r)$  satisfies

$$q(x) + r(y) \geq s(x, y) \geq u(x, z) - v(y, z), \quad \text{on } X \times Y \times Z.$$

Hence

$$v(y, z) + r(y) \geq u(x, z) - q(x)$$

and  $\inf_y (v(y, z) + r(y)) \geq \sup_x (u(x, z) - q(x))$ . This implies existence of  $p(z)$ . In particular, (1) implies that for all  $(x, y, z)$

$$q(x) \geq u(x, z) - p(z), \quad r(y) \geq p(z) - v(y, z). \quad (2)$$

According to the transportational duality

$$q(x) + r(y) = s(x, y) \quad (3)$$

**Remark:** note that the statement of the dual problem is slightly different from the standard formulation (but equivalent).

**Proof:** The solution  $(q, r)$  satisfies

$$q(x) + r(y) \geq s(x, y) \geq u(x, z) - v(y, z), \quad \text{on } X \times Y \times Z.$$

Hence

$$v(y, z) + r(y) \geq u(x, z) - q(x)$$

and  $\inf_y (v(y, z) + r(y)) \geq \sup_x (u(x, z) - q(x))$ . This implies existence of  $p(z)$ . In particular, (1) implies that for all  $(x, y, z)$

$$q(x) \geq u(x, z) - p(z), \quad r(y) \geq p(z) - v(y, z). \quad (2)$$

According to the transportational duality

$$q(x) + r(y) = s(x, y) \quad (3)$$

In addition, according to the definition of  $s$  there exists a contract  $\hat{z}$  such that  $s(x, y) = u(x, \hat{z}) - v(y, \hat{z})$  and we have

$$s(x, y) = u(x, \hat{z}) - v(y, \hat{z}). \quad (4)$$

for every  $(x, y)$  and  $\hat{z} \in Z(x, y)$ . Combining (4) and (3) we get

$$v(y, \hat{z}) + r(y) = p(\hat{z}) = u(x, \hat{z}) - q(x). \quad (5)$$

for  $\gamma$ -a.e.  $(x, y)$  and  $\hat{z} \in Z(x, y)$ .

Since the measure  $\gamma$  has marginals  $\mu$  and  $\nu$ , it remains to show that  $\hat{z}$  maximizes  $u(x, \hat{z}) - p(\hat{z})$  and  $p(\hat{z}) - v(y, \hat{z})$ . But this follows immediately from (2), (5).

In addition, according to the definition of  $s$  there exists a contract  $\hat{z}$  such that  $s(x, y) = u(x, \hat{z}) - v(y, \hat{z})$  and we have

$$s(x, y) = u(x, \hat{z}) - v(y, \hat{z}). \quad (4)$$

for every  $(x, y)$  and  $\hat{z} \in Z(x, y)$ . Combining (4) and (3) we get

$$v(y, \hat{z}) + r(y) = p(\hat{z}) = u(x, \hat{z}) - q(x). \quad (5)$$

for  $\gamma$ -a.e.  $(x, y)$  and  $\hat{z} \in Z(x, y)$ .

Since the measure  $\gamma$  has marginals  $\mu$  and  $\nu$ , it remains to show that  $\hat{z}$  maximizes  $u(x, \hat{z}) - p(\hat{z})$  and  $p(\hat{z}) - v(y, \hat{z})$ . But this follows immediately from (2), (5).

## Generalizations

- **Carlier, Ekeland: [CE]** Generalizations of the hedonic equilibrium/matching problem for the case of several types of participants (more than two).
- **Ghoussoub, Pass:** Multimarginal Monge-Kantorovich problem

We are given

- **spaces**  $X_1, \dots, X_N$
- **cost function**  $c(x_1, \dots, x_N)$
- **probability measures**  $\mu_1, \dots, \mu_N$

Find probability measure  $\pi$  such that

- $Pr_{X_i} \pi = \mu_i$
- The functional  $\int c(x_1, \dots, x_N) d\pi$  attains its minimum.



## Generalizations

- **Carlier, Ekeland: [CE]** Generalizations of the hedonic equilibrium/matching problem for the case of several types of participants (more than two).
- **Ghoussoub, Pass:** Multimarginal Monge-Kantorovich problem

We are given

- **spaces**  $X_1, \dots, X_N$
- **cost function**  $c(x_1, \dots, x_N)$
- **probability measures**  $\mu_1, \dots, \mu_N$

Find probability measure  $\pi$  such that

- $Pr_{X_i} \pi = \mu_i$
- The functional  $\int c(x_1, \dots, x_N) d\pi$  attains its minimum.

## Generalizations

- **Carlier, Ekeland: [CE]** Generalizations of the hedonic equilibrium/matching problem for the case of several types of participants (more than two).
- **Ghoussoub, Pass:** Multimarginal Monge-Kantorovich problem

We are given

- spaces  $X_1, \dots, X_N$
- cost function  $c(x_1, \dots, x_N)$
- probability measures  $\mu_1, \dots, \mu_N$

Find probability measure  $\pi$  such that

- $Pr_{X_i} \pi = \mu_i$
- The functional  $\int c(x_1, \dots, x_N) d\pi$  attains its minimum.

## Generalizations

- **Carlier, Ekeland: [CE]** Generalizations of the hedonic equilibrium/matching problem for the case of several types of participants (more than two).
- **Ghoussoub, Pass:** Multimarginal Monge-Kantorovich problem

We are given

- spaces  $X_1, \dots, X_N$
- cost function  $c(x_1, \dots, x_N)$
- probability measures  $\mu_1, \dots, \mu_N$

Find probability measure  $\pi$  such that

- $Pr_{X_i} \pi = \mu_i$
- The functional  $\int c(x_1, \dots, x_N) d\pi$  attains its minimum.

## Generalizations

- **Carlier, Ekeland: [CE]** Generalizations of the hedonic equilibrium/matching problem for the case of several types of participants (more than two).
- **Ghoussoub, Pass:** Multimarginal Monge-Kantorovich problem

We are given

- **spaces**  $X_1, \dots, X_N$
- **cost function**  $c(x_1, \dots, x_N)$
- **probability measures**  $\mu_1, \dots, \mu_N$

Find probability measure  $\pi$  such that

- $Pr_{X_i} \pi = \mu_i$
- The functional  $\int c(x_1, \dots, x_N) d\pi$  attains its minimum.

## Generalizations

- **Carlier, Ekeland: [CE]** Generalizations of the hedonic equilibrium/matching problem for the case of several types of participants (more than two).
- **Ghoussoub, Pass:** Multimarginal Monge-Kantorovich problem

We are given

- **spaces**  $X_1, \dots, X_N$
- **cost function**  $c(x_1, \dots, x_N)$
- **probability measures**  $\mu_1, \dots, \mu_N$

Find probability measure  $\pi$  such that

- $Pr_{X_i} \pi = \mu_i$
- The functional  $\int c(x_1, \dots, x_N) d\pi$  attains its minimum.

## Generalizations

- **Carlier, Ekeland: [CE]** Generalizations of the hedonic equilibrium/matching problem for the case of several types of participants (more than two).
- **Ghoussoub, Pass:** Multimarginal Monge-Kantorovich problem

We are given

- **spaces**  $X_1, \dots, X_N$
- **cost function**  $c(x_1, \dots, x_N)$
- **probability measures**  $\mu_1, \dots, \mu_N$

Find probability measure  $\pi$  such that

- $Pr_{X_i} \pi = \mu_i$
- The functional  $\int c(x_1, \dots, x_N) d\pi$  attains its minimum.

## Generalizations

- **Carlier, Ekeland: [CE]** Generalizations of the hedonic equilibrium/matching problem for the case of several types of participants (more than two).
- **Ghoussoub, Pass:** Multimarginal Monge-Kantorovich problem

We are given

- **spaces**  $X_1, \dots, X_N$
- **cost function**  $c(x_1, \dots, x_N)$
- **probability measures**  $\mu_1, \dots, \mu_N$

Find probability measure  $\pi$  such that

- $Pr_{X_i} \pi = \mu_i$
- The functional  $\int c(x_1, \dots, x_N) d\pi$  attains its minimum.

## Generalizations

- **Carlier, Ekeland: [CE]** Generalizations of the hedonic equilibrium/matching problem for the case of several types of participants (more than two).
- **Ghoussoub, Pass:** Multimarginal Monge-Kantorovich problem

We are given

- **spaces**  $X_1, \dots, X_N$
- **cost function**  $c(x_1, \dots, x_N)$
- **probability measures**  $\mu_1, \dots, \mu_N$

Find probability measure  $\pi$  such that

- $Pr_{X_i} \pi = \mu_i$
- The functional  $\int c(x_1, \dots, x_N) d\pi$  attains its minimum.



## Generalizations

- **Carlier, Ekeland: [CE]** Generalizations of the hedonic equilibrium/matching problem for the case of several types of participants (more than two).
- **Ghoussoub, Pass:** Multimarginal Monge-Kantorovich problem

We are given

- **spaces**  $X_1, \dots, X_N$
- **cost function**  $c(x_1, \dots, x_N)$
- **probability measures**  $\mu_1, \dots, \mu_N$

Find probability measure  $\pi$  such that

- $Pr_{X_i} \pi = \mu_i$
- The functional  $\int c(x_1, \dots, x_N) d\pi$  attains its minimum.

## Geometry 1. Monge-Ampère equation

Given two measures on  $\mathbb{R}^n$  consider the optimal quadratic transportation mapping

$$T = \nabla\varphi.$$

Assume that  $T$  is smooth and the measures have densities

$$\mu = \varrho_\mu dx, \quad \nu = \varrho_\nu dx.$$

Then the following change of variables formula must hold:

$$\varrho_\nu(\nabla\varphi) \det D^2\varphi = \varrho_\mu. \quad (6)$$

This is a special case of the **Monge-Ampère equation**.

The regularity problem for the Monge-Ampère equation is highly nontrivial. (see works of A.D. Alexandrov, E. Calabi, A.V. Pogorelov, N.V. Krylov, J. Spruck, L. Caffarelli, L. Nirenberg). In geometry there has been a parallel development of a closed direction — the complex Monge-Ampère equation (Sh.-T. Yau, E. Calabi, T. Aubin). The optimal transportation mappings provide **weak** solutions to Monge-Ampère equation (6).

# Inequalities

Optimal transportation technique can be applied for proving many classical inequalities with sharp constants (Brunn-Minkowski, Sobolev, isoperimetric inequality ...).

Example: Talagrand's transportation inequality

Consider the standard Gaussian measure

$$\gamma = \frac{1}{(2\pi)^{d/2}} e^{-\frac{|x|^2}{2}} dx$$

and another probability measure  $\nu = g \cdot \gamma$ .

Let  $W_2(\gamma, g \cdot \gamma)$  be the Kantorovich quadratic distance:

$$W_2(\gamma, g \cdot \gamma) = \left( \inf_{\pi \in \Pi(\gamma, \nu)} \int |x - y|^2 d\pi \right)^{\frac{1}{2}}.$$

# Inequalities

Optimal transportation technique can be applied for proving many classical inequalities with sharp constants (Brunn-Minkowski, Sobolev, isoperimetric inequality ...).

## Example: Talagrand's transportation inequality

Consider the standard Gaussian measure

$$\gamma = \frac{1}{(2\pi)^{d/2}} e^{-\frac{|x|^2}{2}} dx$$

and another probability measure  $\nu = g \cdot \gamma$ .

Let  $W_2(\gamma, g \cdot \gamma)$  be the Kantorovich quadratic distance:

$$W_2(\gamma, g \cdot \gamma) = \left( \inf_{\pi \in \Pi(\gamma, \nu)} \int |x - y|^2 d\pi \right)^{\frac{1}{2}}.$$

# Inequalities

Optimal transportation technique can be applied for proving many classical inequalities with sharp constants (Brunn-Minkowski, Sobolev, isoperimetric inequality ...).

## Example: Talagrand's transportation inequality

Consider the standard Gaussian measure

$$\gamma = \frac{1}{(2\pi)^{d/2}} e^{-\frac{|x|^2}{2}} dx$$

and another probability measure  $\nu = g \cdot \gamma$ .

Let  $W_2(\gamma, g \cdot \gamma)$  be the Kantorovich quadratic distance:

$$W_2(\gamma, g \cdot \gamma) = \left( \inf_{\pi \in \Pi(\gamma, \nu)} \int |x - y|^2 d\pi \right)^{\frac{1}{2}}.$$

## Theorem

$$\frac{1}{2} W_2^2(\gamma, g \cdot \gamma) \leq \text{Ent}_\gamma g, \quad (7)$$

where  $\text{Ent}_\gamma g = \int g \log g \, d\gamma$ .

**More generally:** estimates of the type  $W_p^p(\nu, \mu) \leq \int F\left(\frac{\nu}{\mu}\right) d\mu$  for some  $p \geq 1$  and a function  $F$  are called transportation inequalities.

Why we are interested in transportation inequalities?

1. Let  $\mu$  and  $\nu = f \cdot \mu$  be probability measures and let  $f > 0$ . Then **Kullback-Csiszár-Pinsker** inequality holds

$$\frac{1}{2} \|\mu - \nu\|^2 := \frac{1}{2} \left( \int |f - 1| \, d\mu \right)^2 \leq \text{Ent}_\mu f.$$

Here  $\|\mu - \nu\|$  is the variation distance between  $\mu$  and  $\nu$ . This inequality can be regarded as the transportation inequality for a suitable cost function (Bolley–Villani).

## Theorem

$$\frac{1}{2} W_2^2(\gamma, g \cdot \gamma) \leq \text{Ent}_\gamma g, \quad (7)$$

where  $\text{Ent}_\gamma g = \int g \log g \, d\gamma$ .

**More generally:** estimates of the type  $W_p^p(\nu, \mu) \leq \int F\left(\frac{\nu}{\mu}\right) d\mu$  for some  $p \geq 1$  and a function  $F$  are called transportation inequalities.

Why we are interested in transportation inequalities?

1. Let  $\mu$  and  $\nu = f \cdot \mu$  be probability measures and let  $f > 0$ . Then **Kullback-Csiszár-Pinsker** inequality holds

$$\frac{1}{2} \|\mu - \nu\|^2 := \frac{1}{2} \left( \int |f - 1| \, d\mu \right)^2 \leq \text{Ent}_\mu f.$$

Here  $\|\mu - \nu\|$  is the variation distance between  $\mu$  and  $\nu$ . This inequality can be regarded as the transportation inequality for a suitable cost function (Bolley–Villani).

## Theorem

$$\frac{1}{2} W_2^2(\gamma, g \cdot \gamma) \leq \text{Ent}_\gamma g, \quad (7)$$

where  $\text{Ent}_\gamma g = \int g \log g \, d\gamma$ .

**More generally:** estimates of the type  $W_p^p(\nu, \mu) \leq \int F\left(\frac{\nu}{\mu}\right) d\mu$  for some  $p \geq 1$  and a function  $F$  are called transportation inequalities.

Why we are interested in transportation inequalities?

1. Let  $\mu$  and  $\nu = f \cdot \mu$  be probability measures and let  $f > 0$ . Then **Kullback-Csiszár-Pinsker** inequality holds

$$\frac{1}{2} \|\mu - \nu\|^2 := \frac{1}{2} \left( \int |f - 1| \, d\mu \right)^2 \leq \text{Ent}_\mu f.$$

Here  $\|\mu - \nu\|$  is the variation distance between  $\mu$  and  $\nu$ . This inequality can be regarded as the transportation inequality for a suitable cost function (Bolley–Villani).



## Theorem

$$\frac{1}{2} W_2^2(\gamma, g \cdot \gamma) \leq \text{Ent}_\gamma g, \quad (7)$$

where  $\text{Ent}_\gamma g = \int g \log g \, d\gamma$ .

**More generally:** estimates of the type  $W_p^p(\nu, \mu) \leq \int F\left(\frac{\nu}{\mu}\right) d\mu$  for some  $p \geq 1$  and a function  $F$  are called transportation inequalities.

Why we are interested in transportation inequalities?

1. Let  $\mu$  and  $\nu = f \cdot \mu$  be probability measures and let  $f > 0$ . Then **Kullback-Csiszár-Pinsker** inequality holds

$$\frac{1}{2} \|\mu - \nu\|^2 := \frac{1}{2} \left( \int |f - 1| \, d\mu \right)^2 \leq \text{Ent}_\mu f.$$

Here  $\|\mu - \nu\|$  is the variation distance between  $\mu$  and  $\nu$ . This inequality can be regarded as the transportation inequality for a suitable cost function (Bolley–Villani).

2. Under additional assumptions they are equivalent to Sobolev-type inequalities (e.g. log-Sobolev inequality).
3. They yield the **concentration of measures** phenomenon.
4. This is a natural way to measure distance between solutions to PDE's.
5. Typical application: analysis on Wiener space.

### Lemma

*For any positive symmetric  $d \times d$  matrix  $A$  the following inequality holds*

$$\text{Tr}A - d - \log \det A \geq 0. \quad (8)$$

2. Under additional assumptions they are equivalent to Sobolev-type inequalities (e.g. log-Sobolev inequality).
3. They yield the **concentration of measures** phenomenon.
4. This is a natural way to measure distance between solutions to PDE's.
5. Typical application: analysis on Wiener space.

### Lemma

*For any positive symmetric  $d \times d$  matrix  $A$  the following inequality holds*

$$\text{Tr}A - d - \log \det A \geq 0. \quad (8)$$

2. Under additional assumptions they are equivalent to Sobolev-type inequalities (e.g. log-Sobolev inequality).
3. They yield the **concentration of measures** phenomenon.
4. This is a natural way to measure distance between solutions to PDE's.
5. Typical application: analysis on Wiener space.

### Lemma

*For any positive symmetric  $d \times d$  matrix  $A$  the following inequality holds*

$$\text{Tr}A - d - \log \det A \geq 0. \quad (8)$$

2. Under additional assumptions they are equivalent to Sobolev-type inequalities (e.g. log-Sobolev inequality).
3. They yield the **concentration of measures** phenomenon.
4. This is a natural way to measure distance between solutions to PDE's.
5. Typical application: analysis on Wiener space.

### Lemma

*For any positive symmetric  $d \times d$  matrix  $A$  the following inequality holds*

$$\text{Tr}A - d - \log \det A \geq 0. \quad (8)$$

2. Under additional assumptions they are equivalent to Sobolev-type inequalities (e.g. log-Sobolev inequality).
3. They yield the **concentration of measures** phenomenon.
4. This is a natural way to measure distance between solutions to PDE's.
5. Typical application: analysis on Wiener space.

### Lemma

*For any positive symmetric  $d \times d$  matrix  $A$  the following inequality holds*

$$\text{Tr}A - d - \log \det A \geq 0. \quad (8)$$

**Sketch of the proof:** Let us consider the optimal transportation  $T = \nabla\varphi$  of the measure  $\gamma$  to the measure  $g \cdot \gamma$ . The desired inequality is equivalent to the estimate

$$\frac{1}{2} \int_{\mathbb{R}^d} |x - \nabla\varphi(x)|^2 \gamma(dx) \leq \int_{\mathbb{R}^d} g \ln g d\gamma. \quad (9)$$

For the proof of (7) we consider the change of variables formula

$$-\frac{x^2}{2} = \ln g(\nabla\varphi(x)) - \frac{|\nabla\varphi(x)|^2}{2} + \ln \det D^2\varphi(x).$$

Write it as

$|x - \nabla\varphi(x)|^2/2 = \langle x, x - \nabla\varphi(x) \rangle + \ln g(\nabla\varphi(x)) + \ln \det D^2\varphi(x)$   
and integrate with respect to the measure  $\gamma$ . Note that

$$\int \left( \langle x, x - \nabla\varphi(x) \rangle + \ln \det D^2\varphi(x) \right) d\gamma = \int \left( d - \Delta\varphi + \ln \det D^2\varphi(x) \right) d\gamma.$$

Finally we get (9) from (8).

## Log-Sobolev inequality

Let us consider the optimal transportation  $T = \nabla\varphi$  of the measure  $f^2 \cdot \gamma$  to the measure  $\gamma$ . Apply again the change of variables formula

$$\ln f^2(x) - |x|^2/2 = -|\nabla\varphi(x)|^2/2 + \ln \det D^2\varphi(x).$$

Let us rewrite the obtained equality in the form

$$\ln f^2(x) = -|x - \nabla\varphi(x)|^2/2 - \langle x, \nabla\varphi(x) - x \rangle + \ln \det D^2\varphi(x)$$

and integrate it with respect to the measure  $f^2 \cdot \gamma$ , which gives the relationship

$$\begin{aligned} \int_{\mathbb{R}^d} f^2 \ln f^2 d\gamma &= - \int_{\mathbb{R}^d} \frac{|x - \nabla\varphi(x)|^2}{2} f^2(x) \gamma(dx) - \\ &\quad - \int_{\mathbb{R}^d} \langle x, \nabla\varphi(x) - x \rangle f^2(x) \gamma(dx) + \int_{\mathbb{R}^d} \ln \det D^2\varphi f^2 d\gamma. \end{aligned}$$



Let us apply integration by parts:

$$\begin{aligned} & - \int_{\mathbb{R}^d} \langle x, \nabla \varphi(x) - x \rangle f^2(x) \gamma(dx) = \\ & = 2 \int_{\mathbb{R}^d} \langle \nabla f(x), \nabla \varphi(x) - x \rangle f(x) \gamma(dx) - \int_{\mathbb{R}^d} (\Delta \varphi - d) f^2 d\gamma. \end{aligned}$$

Applying (8) we obtain

$$\begin{aligned} \int_{\mathbb{R}^d} f^2 \ln f^2 d\gamma \leq & \int_{\mathbb{R}^d} \left[ -\frac{|x - \nabla \varphi(x)|^2}{2} f^2(x) \right. \\ & \left. + 2 \langle \nabla f(x), \nabla \varphi(x) - x \rangle f(x) \right] d\gamma(dx). \end{aligned}$$

Finally, we obtain from the estimate

$$-\frac{|x - \nabla \varphi(x)|^2}{2} f^2(x) + 2 \langle \nabla f(x), \nabla \varphi(x) - x \rangle f(x) \leq 2 |\nabla f(x)|^2.$$

## Theorem

**Logarithmic Sobolev inequality.** For every sufficiently regular function  $f$  with  $\int f^2 d\gamma = 1$  one has

$$\int f^2 \log f^2 d\gamma \leq 2 \int |\nabla f(x)|^2 d\gamma.$$

A very famous inequality attributed to L. Gross (1975).

## PDE's and variational calculus

**Philosophy.** The space of measures with the distance  $W_p$  is an **infinite-dimensional** manifold.

The Benamou–Brenier formula (viewpoint of fluid mechanics).

The Benamou–Brenier formula interprets the metric  $W_p(\mathbb{R}^d)$  on the space of  $\mathcal{P}_p(\mathbb{R}^d)$  of probability measures with a finite  $p$ -th moment as the Riemannian **length** on the (infinite-dimensional) manifold.

Let  $v_t: \mathbb{R}^d \rightarrow \mathbb{R}^d$ ,  $t \in [0, 1]$  be a family of smooth vector fields (a velocity field) and let  $T_t: \mathbb{R}^d \rightarrow \mathbb{R}^d$  be the family of transformations generated by it according to the equation

$$\frac{dT_t}{dt} = v_t(T_t), \quad T_0(x) = x.$$

Let us consider the family of measures given by

$$\mu_t = \mu_0 \circ T_t^{-1} = \varrho_t dx, \mu_0 = \varrho_0 dx.$$

It is well-known  $\mu_t$  satisfies the classical continuity equation

$$\frac{\partial \varrho_t}{\partial t} + \operatorname{div}(\varrho_t \cdot v_t) = 0. \quad (10)$$

The following formula (for  $p = 2$ ) was obtained by Benamou and Brenier:

$$W_p^p(\mu_0, \mu_1) = \inf_v \int_0^1 \int |v_t|^p d\mu_t dt,$$

where  $\mu_t = \varrho_t dx$  satisfies (10) and inf is taken over vector fields from some suitable class.

**Interpretation:**  $W_p$  is the **geodesic** distance on the space of measures.

**Idea of the proof:** inequality  $W_p^p(\mu_0, \mu_1) \leq \int_0^1 \int |v_t|^p d\mu_t dt$  follows from the relationships

$$\begin{aligned} W_p^p(\mu_0, \mu_1) &\leq \int |T_t(x) - x|^p \varrho_0 dx \leq \int \int_0^1 \left| \frac{d}{dt} T_t(x) \right|^p dt \varrho_0 dx = \\ &= \int \int_0^1 |v_t|^p(T_t) dt d\mu_0 = \int_0^1 \int |v_t|^p d\mu_t dt. \end{aligned}$$

Equality is attained on  $T_t(x) = (1-t)x + tT(x)$ , where  $T$  is the optimal transportation of  $\mu_0$  to  $\mu_1$  (for  $c = |x - y|^p$ ).

In particular, **geodesics** have a simple description. Any geodesic  $\{\mu_t\}$  has the form  $\mu_t = \mu_0 \cdot T_t$ , where  $T$  is the optimal transportation mapping.

**Idea of the proof:** inequality  $W_p^p(\mu_0, \mu_1) \leq \int_0^1 \int |v_t|^p d\mu_t dt$  follows from the relationships

$$\begin{aligned} W_p^p(\mu_0, \mu_1) &\leq \int |T_t(x) - x|^p \varrho_0 dx \leq \int \int_0^1 \left| \frac{d}{dt} T_t(x) \right|^p dt \varrho_0 dx = \\ &= \int \int_0^1 |v_t|^p(T_t) dt d\mu_0 = \int_0^1 \int |v_t|^p d\mu_t dt. \end{aligned}$$

Equality is attained on  $T_t(x) = (1-t)x + tT(x)$ , where  $T$  is the optimal transportation of  $\mu_0$  to  $\mu_1$  (for  $c = |x - y|^p$ ).

In particular, **geodesics** have a simple description. Any geodesic  $\{\mu_t\}$  has the form  $\mu_t = \mu_0 \cdot T_t$ , where  $T$  is the optimal transportation mapping.

## Gradient flows. Otto calculus.

A gradient flow in  $\mathbb{R}^d$  is a solution  $X(t)$  of the equation

$$dX(t)/dt = -\nabla E(X(t)),$$

where  $E$  is "energy". We observe that

$dE(X(t))/dt = -|\nabla E(X(t))|^2$  (the energy is decreasing).

- It is very helpful to interpret an equation as a gradient flow (existence, uniqueness, rate of convergence, numerical solutions ...).
- **Otto calculus:** a heuristic way to interpret PDE's as gradient flows on the space  $\mathcal{W}_2(\mathbb{R}^n)$  (which is  $\mathbb{P}_2(\mathbb{R}^n)$  endowed with  $\mathcal{W}_2$ -distance).
- **Difficulties:**  $\mathcal{W}_2(\mathbb{R}^n)$  is a non-linear space, but "manifold". There is a natural infinite-dimensional "Riemannian" structure on this space, but it is very difficult to formalize this approach.
- See, however, the book **[AGS]** of Ambrosio, Gigli, and Savaré. Many things can be formalized...

## Gradient flows. Otto calculus.

A gradient flow in  $\mathbb{R}^d$  is a solution  $X(t)$  of the equation

$$dX(t)/dt = -\nabla E(X(t)),$$

where  $E$  is "energy". We observe that

$dE(X(t))/dt = -|\nabla E(X(t))|^2$  (the energy is decreasing).

- It is very helpful to interpret an equation as a gradient flow (existence, uniqueness, rate of convergence, numerical solutions ...).
- **Otto calculus:** a heuristic way to interpret PDE's as gradient flows on the space  $\mathcal{W}_2(\mathbb{R}^n)$  (which is  $\mathbb{P}_2(\mathbb{R}^n)$  endowed with  $W_2$ -distance).
- **Difficulties:**  $\mathcal{W}_2(\mathbb{R}^n)$  is a non-linear space, but "manifold". There is a natural infinite-dimensional "Riemannian" structure on this space, but it is very difficult to formalize this approach.
- See, however, the book **[AGS]** of Ambrosio, Gigli, and Savaré. Many things can be formalized...



## Gradient flows. Otto calculus.

A gradient flow in  $\mathbb{R}^d$  is a solution  $X(t)$  of the equation

$$dX(t)/dt = -\nabla E(X(t)),$$

where  $E$  is "energy". We observe that

$dE(X(t))/dt = -|\nabla E(X(t))|^2$  (the energy is decreasing).

- It is very helpful to interpret an equation as a gradient flow (existence, uniqueness, rate of convergence, numerical solutions ...).
- **Otto calculus:** a heuristic way to interpret PDE's as gradient flows on the space  $\mathcal{W}_2(\mathbb{R}^n)$  (which is  $\mathbb{P}_2(\mathbb{R}^n)$  endowed with  $W_2$ -distance).
- **Difficulties:**  $\mathcal{W}_2(\mathbb{R}^n)$  is a non-linear space, but "manifold". There is a natural infinite-dimensional "Riemannian" structure on this space, but it is very difficult to formalize this approach.
- See, however, the book **[AGS]** of Ambrosio, Gigli, and Savaré. Many things can be formalized...

## Gradient flows. Otto calculus.

A gradient flow in  $\mathbb{R}^d$  is a solution  $X(t)$  of the equation

$$dX(t)/dt = -\nabla E(X(t)),$$

where  $E$  is "energy". We observe that

$dE(X(t))/dt = -|\nabla E(X(t))|^2$  (the energy is decreasing).

- It is very helpful to interpret an equation as a gradient flow (existence, uniqueness, rate of convergence, numerical solutions ...).
- **Otto calculus:** a heuristic way to interpret PDE's as gradient flows on the space  $\mathcal{W}_2(\mathbb{R}^n)$  (which is  $\mathbb{P}_2(\mathbb{R}^n)$  endowed with  $W_2$ -distance).
- **Difficulties:**  $\mathcal{W}_2(\mathbb{R}^n)$  is a non-linear space, but "manifold". There is a natural infinite-dimensional "Riemannian" structure on this space, but it is very difficult to formalize this approach.
- See, however, the book **[AGS]** of Ambrosio, Gigli, and Savaré. Many things can be formalized...

## Gradient flows. Otto calculus.

A gradient flow in  $\mathbb{R}^d$  is a solution  $X(t)$  of the equation

$$dX(t)/dt = -\nabla E(X(t)),$$

where  $E$  is "energy". We observe that

$dE(X(t))/dt = -|\nabla E(X(t))|^2$  (the energy is decreasing).

- It is very helpful to interpret an equation as a gradient flow (existence, uniqueness, rate of convergence, numerical solutions ...).
- **Otto calculus:** a heuristic way to interpret PDE's as gradient flows on the space  $\mathcal{W}_2(\mathbb{R}^n)$  (which is  $\mathbb{P}_2(\mathbb{R}^n)$  endowed with  $\mathcal{W}_2$ -distance).
- **Difficulties:**  $\mathcal{W}_2(\mathbb{R}^n)$  is a non-linear space, but "manifold". There is a natural infinite-dimensional "Riemannian" structure on this space, but it is very difficult to formalize this approach.
- See, however, the book **[AGS]** of Ambrosio, Gigli, and Savaré. Many things can be formalized...

## Energy functionals and their gradient flows

The heat equation

$$E(\mu) = \int \varrho \log \rho \, dx, \quad \frac{\partial \varrho}{\partial t} = \Delta \varrho.$$

The porous media equation:

$$E(\mu) = \frac{1}{m-1} \int \varrho^m \, dx, \quad \frac{\partial \varrho}{\partial t} = \Delta \varrho^m.$$

The McKean–Vlasov equation:

$$E(\mu) = \frac{1}{2} \int W(x-y) \varrho(x) \varrho(y) \, dx dy, \quad \frac{\partial \varrho}{\partial t} = \operatorname{div}(\varrho \nabla(\varrho * \nabla W)).$$

The quantum drift-diffusion equation:

$$E(\mu) = \int \frac{|\nabla \varrho|^2}{\varrho} \, dx, \quad \frac{\partial \varrho}{\partial t} + 4 \operatorname{div} \left( \varrho \nabla \frac{\Delta \sqrt{\varrho}}{\sqrt{\varrho}} \right) = 0.$$

To compute the gradients of the functionals we need

- Tangent space
- $L^2$ -structure on this space (Riemannian metric)

## F. Otto:

- The tangent space  $TP^2(\mathbb{R}^d)$  at a point  $\varrho dx$  consists of all measures with densities of the form  $-\operatorname{div}(\varrho \nabla u)$ , where  $u$  is a function.
- Define the Riemannian metric on  $TP^2(\mathbb{R}^d)$  as follows:

$$\int_{\mathbb{R}^d} \langle \nabla u_1, \nabla u_2 \rangle \varrho dx.$$

To compute the gradients of the functionals we need

- Tangent space
- $L^2$ -structure on this space (Riemannian metric)

## F. Otto:

- The tangent space  $TP^2(\mathbb{R}^d)$  at a point  $\varrho dx$  consists of all measures with densities of the form  $-\operatorname{div}(\varrho \nabla u)$ , where  $u$  is a function.
- Define the Riemannian metric on  $TP^2(\mathbb{R}^d)$  as follows:

$$\int_{\mathbb{R}^d} \langle \nabla u_1, \nabla u_2 \rangle \varrho dx.$$

To compute the gradients of the functionals we need

- Tangent space
- $L^2$ -structure on this space (Riemannian metric)

## F. Otto:

- The tangent space  $TP^2(\mathbb{R}^d)$  at a point  $\rho dx$  consists of all measures with densities of the form  $-\operatorname{div}(\rho \nabla u)$ , where  $u$  is a function.
- Define the Riemannian metric on  $TP^2(\mathbb{R}^d)$  as follows:

$$\int_{\mathbb{R}^d} \langle \nabla u_1, \nabla u_2 \rangle \rho dx.$$

To compute the gradients of the functionals we need

- Tangent space
- $L^2$ -structure on this space (Riemannian metric)

## F. Otto:

- The tangent space  $T\mathcal{P}^2(\mathbb{R}^d)$  at a point  $\varrho dx$  consists of all measures with densities of the form  $-\operatorname{div}(\varrho \nabla u)$ , where  $u$  is a function.
- Define the Riemannian metric on  $T\mathcal{P}^2(\mathbb{R}^d)$  as follows:

$$\int_{\mathbb{R}^d} \langle \nabla u_1, \nabla u_2 \rangle \varrho dx.$$



To compute the gradients of the functionals we need

- Tangent space
- $L^2$ -structure on this space (Riemannian metric)

## F. Otto:

- The tangent space  $T\mathcal{P}^2(\mathbb{R}^d)$  at a point  $\varrho dx$  consists of all measures with densities of the form  $-\operatorname{div}(\varrho \nabla u)$ , where  $u$  is a function.
- Define the Riemannian metric on  $T\mathcal{P}^2(\mathbb{R}^d)$  as follows:

$$\int_{\mathbb{R}^d} \langle \nabla u_1, \nabla u_2 \rangle \varrho dx.$$

To compute the gradients of the functionals we need

- Tangent space
- $L^2$ -structure on this space (Riemannian metric)

## F. Otto:

- The tangent space  $T\mathcal{P}^2(\mathbb{R}^d)$  at a point  $\varrho dx$  consists of all measures with densities of the form  $-\operatorname{div}(\varrho \nabla u)$ , where  $u$  is a function.
- Define the Riemannian metric on  $T\mathcal{P}^2(\mathbb{R}^d)$  as follows:

$$\int_{\mathbb{R}^d} \langle \nabla u_1, \nabla u_2 \rangle \varrho dx.$$

## Computation of the gradient of the entropy functional

Let us consider the entropy functional

$$\text{Ent}: \rho \, dx \mapsto \int_{\mathbb{R}^d} \rho \ln \rho \, dx.$$

Differentiate it along a geodesic  $t \mapsto \mu_0 \circ T_t^{-1}$ . Let us use the change of variables formula

$\rho_t((1-t)x + t\nabla\varphi) \det((1-t)I + tD^2\varphi) = \rho_0$ . Using infinitesimal expansion at  $t=0$  we get

$$\langle \nabla \rho, \nabla \varphi - x \rangle + \dot{\rho}|_{t=0} + \rho(\Delta\varphi - d) = 0, \quad (11)$$

$$\begin{aligned} \frac{\partial \text{Ent}_{\rho_t}}{\partial t} \Big|_{t=0} &= \frac{d}{dt} \int \log \rho_t(T_t) \rho_0 \, dx \Big|_{t=0} = - \int_{\mathbb{R}^d} \rho(\Delta\varphi - d) \, dx \\ &= \int_{\mathbb{R}^d} \langle \nabla \rho, \nabla \psi \rangle \, dx, \end{aligned}$$

where  $\psi(x) = \varphi(x) - |x|^2/2$ .

We observe that according to (11)

$$\frac{\partial \varrho_t}{\partial t} \Big|_{t=0} + \operatorname{div}(\nabla \psi \cdot \varrho_0) = 0.$$

Therefore, the gradient of the functional Ent satisfies the equalities

$$\begin{aligned} \left\langle \nabla \operatorname{Ent}(\varrho), \frac{\partial \varrho_t}{\partial t} \right\rangle \Big|_{t=0} &:= \frac{\partial \operatorname{Ent} \varrho_t}{\partial t} \Big|_{t=0} = \int_{\mathbb{R}^d} \langle \nabla \varrho_0, \nabla \psi \rangle dx \\ &= \int_{\mathbb{R}^d} \left\langle \frac{\nabla \varrho_0}{\varrho_0}, \nabla \psi \right\rangle \varrho_0 dx, \end{aligned}$$

and  $\nabla \operatorname{Ent}(\varrho) \Big|_{t=0}$  is identified with the function

$-\operatorname{div} \left( \varrho_0 \frac{\nabla \varrho_0}{\varrho_0} \right) = -\Delta \varrho_0$  (see the definition of the Riemannian structure!).

Finally we get, that  $\nabla \operatorname{Ent}(\varrho) = -\Delta \varrho$ , this corresponds to the heat equation  $\dot{u} = \Delta u$ .

- It can be shown that the entropy functional is **convex**

$$\frac{d^2}{dt^2} \text{Ent}(\mu_t) \geq 0$$

along geodesics. This leads to numerous applications (Sobolev-type inequalities, existence/uniqueness of solutions etc.).

- Consider the Fokker-Planck equation

$$\frac{\partial \mu_t}{\partial t} = \Delta \mu_t + \text{div}(\nabla V \cdot \mu_t),$$

where  $\mu_t = \rho_t dx$  is probability measure and  $D^2V \geq K \cdot \text{Id}$ . Similarly to example with the entropy one can compute that

$$\frac{d}{dt} W_2^2(\mu_t, \nu_t) \leq -2K \cdot W_2^2(\mu_t, \nu_t).$$

for two different solutions. In particular,

$$W_2(\mu_t, \nu_t) \leq W_2(\mu_0, \nu_0) e^{-Kt}.$$

We have exponential convergence to the invariant measure if  $K > 0$ .

- It can be shown that the entropy functional is **convex**

$$\frac{d^2}{dt^2} \text{Ent}(\mu_t) \geq 0$$

along geodesics. This leads to numerous applications (Sobolev-type inequalities, existence/uniqueness of solutions etc.).

- Consider the Fokker-Planck equation

$$\frac{\partial \mu_t}{\partial t} = \Delta \mu_t + \text{div}(\nabla V \cdot \mu_t),$$

where  $\mu_t = \rho_t dx$  is probability measure and  $D^2V \geq K \cdot \text{Id}$ . Similarly to example with the entropy one can compute that

$$\frac{d}{dt} W_2^2(\mu_t, \nu_t) \leq -2K \cdot W_2^2(\mu_t, \nu_t).$$

for two different solutions. In particular,

$$W_2(\mu_t, \nu_t) \leq W_2(\mu_0, \nu_0) e^{-Kt}.$$

We have exponential convergence to the invariant measure if  $K > 0$ .

## Geometry 2

### Positively curved spaces

Consider **Riemannian manifold with density**, i.e. manifold  $M$  with metric  $g$  and probability measure  $e^{-V} dx$ , where  $dx$  is the Riemannian volume.

Its **Bakry-Emery tensor**

$$BE = \text{Ric} + D^2V,$$

where  $\text{Ric}$  is the Ricci tensor of  $M$  and  $D^2V$  is the Riemannian Hessian of  $V$ , is responsible for analytical properties of manifolds.

### Theorem

**(Bakry-Emery (1985))**. Let  $M$  be a Riemannian manifold with a probability measure  $\mu = e^{-V} dx$ , where  $dx$  is the Riemannian volume. If  $BE \geq K \cdot g$ ,  $K > 0$ , then there holds the logarithmic

Sobolev inequality  $\text{Ent}_\mu f^2 \leq \frac{2}{K} \int_M |\nabla f|^2 d\mu$ .

## Geometry 2

### Positively curved spaces

Consider **Riemannian manifold with density**, i.e. manifold  $M$  with metric  $g$  and probability measure  $e^{-V} dx$ , where  $dx$  is the Riemannian volume.

Its **Bakry-Emery tensor**

$$BE = \text{Ric} + D^2V,$$

where  $\text{Ric}$  is the Ricci tensor of  $M$  and  $D^2V$  is the Riemannian Hessian of  $V$ , is responsible for analytical properties of manifolds.

### Theorem

**(Bakry-Emery (1985))**. Let  $M$  be a Riemannian manifold with a probability measure  $\mu = e^{-V} dx$ , where  $dx$  is the Riemannian volume. If  $BE \geq K \cdot g$ ,  $K > 0$ , then there holds the logarithmic

Sobolev inequality  $\text{Ent}_\mu f^2 \leq \frac{2}{K} \int_M |\nabla f|^2 d\mu$ .



## Theorem

**(Characterization of the property  $BE \geq K \cdot g$ .)** A smooth manifold  $M$  with a measure  $\nu = e^{-V} dx$ , where  $V \in C^2(M)$  satisfies  $BE \geq K \cdot g$ , precisely when the entropy functional

$$\mathcal{F}(\mu) = \int_M \varrho \ln \varrho d\nu, \quad \mu = \rho \cdot \nu,$$

is  $K$ -convex on  $\mathcal{W}_2(M)$ .

$K$ -convexity means that  $\frac{d^2}{dt^2} \mathcal{F}(\mu_t) \geq K$ , where  $\{\mu_t\}$  is a geodesic family of measures.

This characterization can be used to define positively curved **non-smooth** spaces: Gromov-Hausdorff limits of smooth manifolds, infinite-dimensional spaces etc. (**C. Villani, K.-T. Sturm, J. Lott**)

## Theorem

**(Characterization of the property  $BE \geq K \cdot g$ .)** A smooth manifold  $M$  with a measure  $\nu = e^{-V} dx$ , where  $V \in C^2(M)$  satisfies  $BE \geq K \cdot g$ , precisely when the entropy functional

$$\mathcal{F}(\mu) = \int_M \varrho \ln \varrho d\nu, \quad \mu = \rho \cdot \nu,$$

is  $K$ -convex on  $\mathcal{W}_2(M)$ .

$K$ -convexity means that  $\frac{d^2}{dt^2} \mathcal{F}(\mu_t) \geq K$ , where  $\{\mu_t\}$  is a geodesic family of measures.

This characterization can be used to define positively curved **non-smooth** spaces: Gromov-Hausdorff limits of smooth manifolds, infinite-dimensional spaces etc. (**C. Villani, K.-T. Sturm, J. Lott**)

## Theorem

**(Characterization of the property  $BE \geq K \cdot g$ .)** A smooth manifold  $M$  with a measure  $\nu = e^{-V} dx$ , where  $V \in C^2(M)$  satisfies  $BE \geq K \cdot g$ , precisely when the entropy functional

$$\mathcal{F}(\mu) = \int_M \varrho \ln \varrho d\nu, \quad \mu = \rho \cdot \nu,$$

is  $K$ -convex on  $\mathcal{W}_2(M)$ .

$K$ -convexity means that  $\frac{d^2}{dt^2} \mathcal{F}(\mu_t) \geq K$ , where  $\{\mu_t\}$  is a geodesic family of measures.

This characterization can be used to define positively curved **non-smooth** spaces: Gromov-Hausdorff limits of smooth manifolds, infinite-dimensional spaces etc. (**C. Villani, K.-T. Sturm, J. Lott**)

## Other applications in geometry

- Generalizations of geometrical (comparison theorems) and analytical (isoperimetric inequalities) results for the case of manifolds with densities
- There are many works on optimal transportation on manifolds (in particular, regularity issues).
- Ricci flows from the transportational viewpoint. It is possible to recover some of the crucial Perelman's estimates using optimal transportation (**Topping, McCann (09)**)
- **Oliker (07)** The cost function  $-\log\langle x, y \rangle$  leads to transportational solution of a Minkowski-type problem solved earlier by A.D. Alexandrov
- Weak solutions to Gauss curvature flows (**V. Bogachev, K.(09)**)

## Other applications in geometry

- Generalizations of geometrical (comparison theorems) and analytical (isoperimetric inequalities) results for the case of manifolds with densities
- There are many works on optimal transportation on manifolds (in particular, regularity issues).
- Ricci flows from the transportational viewpoint. It is possible to recover some of the crucial Perelman's estimates using optimal transportation (**Topping, McCann (09)**)
- **Oliker (07)** The cost function  $-\log\langle x, y \rangle$  leads to transportational solution of a Minkowski-type problem solved earlier by A.D. Alexandrov
- Weak solutions to Gauss curvature flows (**V. Bogachev, K.(09)**)

## Other applications in geometry

- Generalizations of geometrical (comparison theorems) and analytical (isoperimetric inequalities) results for the case of manifolds with densities
- There are many works on optimal transportation on manifolds (in particular, regularity issues).
- Ricci flows from the transportational viewpoint. It is possible to recover some of the crucial Perelman's estimates using optimal transportation (**Topping, McCann (09)**)
- **Oliker (07)** The cost function  $-\log\langle x, y \rangle$  leads to transportational solution of a Minkowski-type problem solved earlier by A.D. Alexandrov
- Weak solutions to Gauss curvature flows (**V. Bogachev, K.(09)**)

## Other applications in geometry

- Generalizations of geometrical (comparison theorems) and analytical (isoperimetric inequalities) results for the case of manifolds with densities
- There are many works on optimal transportation on manifolds (in particular, regularity issues).
- Ricci flows from the transportational viewpoint. It is possible to recover some of the crucial Perelman's estimates using optimal transportation (**Topping, McCann (09)**)
- **Oliker (07)** The cost function  $-\log\langle x, y \rangle$  leads to transportational solution of a Minkowski-type problem solved earlier by A.D. Alexandrov
- Weak solutions to Gauss curvature flows (**V. Bogachev, K.(09)**)

## Other applications in geometry

- Generalizations of geometrical (comparison theorems) and analytical (isoperimetric inequalities) results for the case of manifolds with densities
- There are many works on optimal transportation on manifolds (in particular, regularity issues).
- Ricci flows from the transportational viewpoint. It is possible to recover some of the crucial Perelman's estimates using optimal transportation (**Topping, McCann (09)**)
- **Oliker (07)** The cost function  $-\log\langle x, y \rangle$  leads to transportational solution of a Minkowski-type problem solved earlier by A.D. Alexandrov
- Weak solutions to Gauss curvature flows (**V. Bogachev, K.(09)**)



## Other applications in geometry

- Generalizations of geometrical (comparison theorems) and analytical (isoperimetric inequalities) results for the case of manifolds with densities
- There are many works on optimal transportation on manifolds (in particular, regularity issues).
- Ricci flows from the transportational viewpoint. It is possible to recover some of the crucial Perelman's estimates using optimal transportation (**Topping, McCann (09)**)
- **Oliker (07)** The cost function  $-\log\langle x, y \rangle$  leads to transportational solution of a Minkowski-type problem solved earlier by A.D. Alexandrov
- Weak solutions to Gauss curvature flows (**V. Bogachev, K.(09)**)

## Infinite-dimensional analysis

- **Analysis on Wiener space.** Let  $\gamma$  be a Gaussian measure and  $(H, |\cdot|)$  its Cameron-Martin space.  
**Problem.** Given a measure  $\nu = g \cdot \gamma$  find a solution to the following Monge problem

$$\int |T(x) - x|^2 d\gamma \rightarrow \inf, \quad (12)$$

where the infimum is taken over mappings  $T$  transforming  $\gamma$  to  $\nu$ .

- Solution to (12) exists under quite general assumptions (Feyel-Üstünel; K.)  
The optimal transportation mapping has the form

$$T(x) = x + \nabla\varphi(x),$$

where  $\varphi$  satisfied  $\partial_{hh}^2\varphi + 1 \geq 0$  for every  $h \in H, |h| \leq 1$ .  
There is no  $\Phi$  such that  $T = \nabla\Phi!$

## Infinite-dimensional analysis

- **Analysis on Wiener space.** Let  $\gamma$  be a Gaussian measure and  $(H, |\cdot|)$  its Cameron-Martin space.

**Problem.** Given a measure  $\nu = g \cdot \gamma$  find a solution to the following Monge problem

$$\int |T(x) - x|^2 d\gamma \rightarrow \inf, \quad (12)$$

where the infimum is taken over mappings  $T$  transforming  $\gamma$  to  $\nu$ .

- Solution to (12) exists under quite general assumptions (**Feyel-Üstünel; K.**)

The optimal transportation mapping has the form

$$T(x) = x + \nabla\varphi(x),$$

where  $\varphi$  satisfied  $\partial_{hh}^2\varphi + 1 \geq 0$  for every  $h \in H, |h| \leq 1$ .

There is no  $\Phi$  such that  $T = \nabla\Phi!$

- Change of variables formula (**V. Bogachev, K.**)

$$g = \det_2(I + D^2\varphi)e^{\mathcal{L}\varphi - \frac{1}{2}|\nabla\varphi|^2},$$

where  $\det_2$  is the Fredholm–Carleman determinant (for  $A : \mathbb{R}^n \rightarrow \mathbb{R}^n$  it can be defined by the formula  $\det_2 A := e^{\text{Tr}(I-A)} \det A$ ),  $\mathcal{L}\varphi$  is the Gaussian "Laplacian"  
 $\mathcal{L}\varphi = \Delta\varphi - \langle x, \nabla\varphi \rangle$ .

- Sufficient conditions for Sobolev regularity of the solution  
**([BK])**

### Theorem

Let  $T(x) = x + \nabla\varphi$  be optimal transportation mapping of  $g \cdot \gamma$  to  $\gamma$ . Then

$$\begin{aligned}
 I_\gamma g &= 2\text{Ent}_\gamma g - 2 \int \log \det_2(\text{Id} + D^2\varphi) g d\gamma & (13) \\
 &+ \int \|D^2\varphi\|_{HS}^2 g d\gamma + \sum_{k=1}^{\infty} \int \text{Tr}[(I + D^2\varphi)^{-1} D^2\varphi_{x_k}]^2 g d\gamma,
 \end{aligned}$$

where  $I_\gamma g = \int \frac{|\nabla g|^2}{g} d\gamma$  (relative information),

$\text{Ent}_\gamma g = \int g \log g d\gamma$  (relative entropy).  $\|D^2\varphi\|_{HS}$  is the Hilber-Schmidt norm of  $D^2\varphi$ .

All the terms in (13) are nonnegative. Theorem contains 1) log-Sobolev inequality, 2) a priori estimate of Sobolev norms of  $\varphi$ .

- Sufficient conditions for Sobolev regularity of the solution  
**([BK])**

### Theorem

Let  $T(x) = x + \nabla\varphi$  be optimal transportation mapping of  $g \cdot \gamma$  to  $\gamma$ . Then

$$\begin{aligned}
 I_\gamma g &= 2\text{Ent}_\gamma g - 2 \int \log \det_2(\text{Id} + D^2\varphi) g d\gamma & (13) \\
 &+ \int \|D^2\varphi\|_{HS}^2 g d\gamma + \sum_{k=1}^{\infty} \int \text{Tr}[(I + D^2\varphi)^{-1} D^2\varphi_{x_k}]^2 g d\gamma,
 \end{aligned}$$

where  $I_\gamma g = \int \frac{|\nabla g|^2}{g} d\gamma$  (relative information),

$\text{Ent}_\gamma g = \int g \log g d\gamma$  (relative entropy).  $\|D^2\varphi\|_{HS}$  is the Hilber-Schmidt norm of  $D^2\varphi$ .

All the terms in (13) are nonnegative. Theorem contains 1) log-Sobolev inequality, 2) a priori estimate of Sobolev norms of  $\varphi$ .

- Sufficient conditions for Sobolev regularity of the solution ([BK])

### Theorem

Let  $T(x) = x + \nabla\varphi$  be optimal transportation mapping of  $g \cdot \gamma$  to  $\gamma$ . Then

$$I_\gamma g = 2\text{Ent}_\gamma g - 2 \int \log \det_2(\text{Id} + D^2\varphi) g d\gamma \quad (13)$$

$$+ \int \|D^2\varphi\|_{HS}^2 g d\gamma + \sum_{k=1}^{\infty} \int \text{Tr}[(I + D^2\varphi)^{-1} D^2\varphi_{x_k}]^2 g d\gamma,$$

where  $I_\gamma g = \int \frac{|\nabla g|^2}{g} d\gamma$  (relative information),

$\text{Ent}_\gamma g = \int g \log g d\gamma$  (relative entropy).  $\|D^2\varphi\|_{HS}$  is the Hilber-Schmidt norm of  $D^2\varphi$ .

All the terms in (13) are nonnegative. Theorem contains 1) log-Sobolev inequality, 2) a priori estimate of Sobolev norms of  $\varphi$ .

- Optimal transport of martingale measures (very recent)  
**Beiglböck, Shachermayer, Soner, Touzi, ...**
- Optimal transportation for measures which are **mutually singular**. ([KZ] )

**Problem:** when there exists "optimal" transportation for mutual singular measures?

**Motivating example:** (Transportation exists but it is not a minimizer of some Monge functional)

1) Let  $\mu = \prod_{i=1}^{\infty} \mu_i(dx_i)$ ,  $\nu = \prod_{i=1}^{\infty} \nu_i(dx_i)$  be product probability measures. Assume that  $\mu_i, \nu_i$  have densities. Set

$T(x) = (T_1(x_1), \dots, T_i(x_i), \dots)$ , where  $T_n(x_n)$  is the one-dimensional optimal transportation sending  $\mu_i$  to  $\nu_i$ .

2)  $\gamma$  is a Gaussian measure and  $\mu$  is obtained from  $\gamma$  by a **linear** mapping  $T(x) = Ax$  with  $A$  symmetric and positive. The measures  $\gamma$  and  $\mu$  are mutually singular even in the simplest case  $A = 2 \cdot \text{Id}$ .

$T$  is "optimal" because it is linear and given by a positive symmetric operator. Heuristically,  $T(x) = \frac{1}{2} \nabla \langle Ax, x \rangle$ .



- Optimal transport of martingale measures (very recent)  
**Beiglböck, Shachermayer, Soner, Touzi, ...**
- Optimal transportation for measures which are **mutually singular**. ([KZ] )

**Problem:** when there exists "optimal" transportation for mutual singular measures?

**Motivating example:** (Transportation exists but it is not a minimizer of some Monge functional)

1) Let  $\mu = \prod_{i=1}^{\infty} \mu_i(dx_i)$ ,  $\nu = \prod_{i=1}^{\infty} \nu_i(dx_i)$  be product probability measures. Assume that  $\mu_i, \nu_i$  have densities. Set

$T(x) = (T_1(x_1), \dots, T_i(x_i), \dots)$ , where  $T_n(x_n)$  is the one-dimensional optimal transportation sending  $\mu_i$  to  $\nu_i$ .

2)  $\gamma$  is a Gaussian measure and  $\mu$  is obtained from  $\gamma$  by a **linear** mapping  $T(x) = Ax$  with  $A$  symmetric and positive. The measures  $\gamma$  and  $\mu$  are mutually singular even in the simplest case  $A = 2 \cdot \text{Id}$ .

$T$  is "optimal" because it is linear and given by a positive symmetric operator. Heuristically,  $T(x) = \frac{1}{2} \nabla \langle Ax, x \rangle$ .

- Optimal transport of martingale measures (very recent)  
**Beiglböck, Shachermayer, Soner, Touzi, ...**
- Optimal transportation for measures which are **mutually singular**. ([KZ] )

**Problem:** when there exists "optimal" transportation for mutual singular measures?

**Motivating example:** (Transportation exists but it is not a minimizer of some Monge functional)

**1)** Let  $\mu = \prod_{i=1}^{\infty} \mu_i(dx_i)$ ,  $\nu = \prod_{i=1}^{\infty} \nu_i(dx_i)$  be product probability measures. Assume that  $\mu_i, \nu_i$  have densities. Set

$T(x) = (T_1(x_1), \dots, T_i(x_i), \dots)$ , where  $T_n(x_n)$  is the one-dimensional optimal transportation sending  $\mu_i$  to  $\nu_i$ .

**2)**  $\gamma$  is a Gaussian measure and  $\mu$  is obtained from  $\gamma$  by a **linear** mapping  $T(x) = Ax$  with  $A$  symmetric and positive. The measures  $\gamma$  and  $\mu$  are mutually singular even in the simplest case  $A = 2 \cdot \text{Id}$ .

$T$  is "optimal" because it is linear and given by a positive symmetric operator. Heuristically,  $T(x) = \frac{1}{2} \nabla \langle Ax, x \rangle$ .

**Counterexample.** (Reason for non-existence: absence of ergodicity)

Let  $\mu = \gamma$  be the standard Gaussian measure on  $\mathbb{R}^\infty$  and

$$\nu = \frac{1}{2}(\gamma + \gamma_2)$$

be the average of  $\gamma$  and its homothetic image  $\gamma_2 = \gamma \circ S^{-1}$ , where  $S(x) = 2x$ . There is no any mass transportation  $T$  of  $\mu$  to  $\nu$  which preserves "rotational invariance" or even exchangeability of a set (i.e., if  $A$  is invariant with respect to cylindrical rotations, then  $T(A)$  is invariant too). Indeed, any mapping of such a type must have the form  $T(x) = g(x)(x_1, x_2, \dots) = g(x) \cdot x$ , where  $g$  is invariant with respect to any "rotation", in particular, with respect to any coordinate permutation. But any function  $g$  of this type is constant  $\gamma$ -a.e. This is a corollary of the Hewitt–Savage 0 – 1 law. It is clear that there is no any mass transportation of this type for the given target measure.

## Approach

**[KZ]**. Consider measures which are invariant w.r.t. some sufficiently rich group (permutations of coordinates, Bernoulli shifts). Instead of minimizing the Monge functional

$$\int \sum_{i=1}^{\infty} |T_i(x) - x_i|^2 d\mu$$

minimize

$$\int |T_1(x) - x_1|^2 d\mu.$$

These formulations are equivalent for in the finite-dimensional case (due to symmetry).

This problem is far from being well understood. Is it true that transportation exists for a large class of ergodic measures?

**A positive result:** consider a Gibbs measure  $\mu$  which can be formally written in the form

$$\mu = e^{-H(x)} dx,$$

where the potential  $H$  admits the following heuristic representation:

$$H(x) = \sum_{i=-\infty}^{+\infty} V(x_i) + \sum_{i=-\infty}^{+\infty} W(x_i, x_{i+1}).$$

Under reasonable assumptions there exists optimal transportation of  $\mu$  onto the standard Gaussian product measure on  $\mathbb{R}^\infty$

$$\gamma = \prod_{i=1}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{x_i^2}{2}} dx_i.$$

## References

- AGS** AMBROSIO L., GIGLI N., SAVARÉ G., Gradient flows in metric spaces and in the Wasserstein spaces of probability measures, Birkhäuser, Basel, 2005.
- BK** BOGACHEV V., KOLESNIKOV A. Sobolev regularity for the Monge-Ampere equation in the Wiener space.  
<http://arxiv.org/abs/1110.1822>.
- CE** CARLIER G., EKELAND I., Matching for teams. Econ Theory (2010) 42:397–418
- CMcN** CHIAPPORI P.A, MCCANN R.J., NESHEIM L.P. , Hedonic price equilibria, stable matching, and optimal transport: equivalence, topology, and uniqueness. Econ Theory (2010) 42:317–354
- Ekeland** EKELAND I., Existence, uniqueness and efficiency of equilibrium in hedonic markets with multidimensional types. Econ Theory (2010) 42:275–315.

## References

- KZ** KOLESNIKOV A., ZAEV D. Optimal transportation of processes with infinite Kantorovich distance. Independence and symmetry. <http://arxiv.org/abs/1303.7255>
- Vill** VILLANI C., Topics in optimal transportation, Amer. Math. Soc. Providence, Rhode Island, 2003.
- Vill2** VILLANI C., Optimal transport, old and new, Springer, New York, 2009.